Domain chaos puzzle and the calculation of the structure factor and its half-width

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The disagreement of the scaling of the correlation length ξ between experiment and the Ginzburg-Landau (GL) model for domain chaos was resolved. The Swift-Hohenberg (SH) domain chaos model was integrated numerically to acquire test images to study the effect of a finite image size on the extraction of ξ from the structure factor (SF). The finite image size had a significant effect on the SF determined with the Fourier-transform (FT) method. The maximum entropy method (MEM) was able to overcome this finite image-size problem and produced fairly accurate SFs for the relatively small image sizes provided by experiments. Correlation lengths often have been determined from the second moment of the SF of chaotic patterns because the functional form of the SF is not known. Integration of several test functions provided analytic results indicating that this may not be a reliable method of extracting ξ . For both a Gaussian and a squared SH form, the correlation length $\bar{\xi} \equiv 1/\sigma$, determined from the variance σ^2 of the SF, has the same dependence on the control parameter ε as the length ξ contained explicitly in the functional forms. However, for the SH and the Lorentzian forms we find $\overline{\xi} \sim \xi^{1/2}$. Results for ξ determined from new experimental data by fitting the functional forms directly to the experimental SF yielded $\xi \sim \varepsilon^{-\nu}$ with $\nu \simeq \frac{1}{4}$ for all four functions in the case of the FT method, but $\nu \simeq \frac{1}{2}$, in agreement with the GL prediction, in the case of the MEM. Over a wide range of ε and wave number k, the experimental SFs collapsed onto a unique curve when appropriately scaled by ξ .

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I. INTRODUCTION

Spatially extended nonlinear nonequilibrium systems continue to be of great interest because they yield qualitatively different phenomena that do not occur in linear systems [1]. One of these phenomena is spatiotemporal chaos. The examples of spatiotemporal chaos found in Rayleigh-Bénard convection (RBC) lend themselves to particularly detailed experimental study under exceptionally well-controlled external conditions [2]. RBC occurs in a thin horizontal layer of fluid with thickness *d* heated from below when the temperature difference ΔT exceeds a critical value ΔT_c [3].

Particularly worth noting is the state that occurs in RBC when the fluid layer of density ρ and shear viscosity η is rotated about a vertical axis with angular frequency ω . When the dimensionless frequency $\Omega \equiv \omega d^2 \rho / \eta$ exceeds a critical value, then the pattern immediately above the onset consists of disordered domains of convection rolls known as domain chaos. This is illustrated in Figs. 1(a) and 1(b). Within each domain the roll orientation is more or less uniform; but different domains have different orientations [4–11]. The domains are unstable and undergo a persistent but irregular dynamics. In this case, the time-averaged mean-square velocities and temperature deviations from the conduction state grow continuously from zero as ΔT_c is exceeded, i.e., the bifurcation is supercritical.

Chaos immediately above a supercritical bifurcation offers a unique opportunity for theoretical study because weakly nonlinear theories are expected to be applicable. These theories, in the form of Ginzburg-Landau (GL) or Swift-Hohenberg (SH) equations, by virtue of their general structure and from their numerical solutions, predict that the inverse half-width at half-height ξ of the structure factor (SF, the power spectrum of the pattern) should vary as $\varepsilon^{-\nu}$ with $\nu = \frac{1}{2}$ as $\varepsilon \equiv \Delta T / \Delta T_c - 1$ vanishes [13–19], and that it is theonly length scale in the problem. Thus it was particularly disappointing that measurements for domain chaos disagreed with this expectation [9]. Determinations of a correlation length $\overline{\xi}$ based on the variance of the SF found $\overline{\xi} \propto \varepsilon^{-\nu_{eff}}$ with $\nu_{eff} \approx \frac{1}{4}$ rather than $\frac{1}{2}$.

Several possible explanations of the apparent disagreement with theory were explored by various authors. Hu *et al.* proposed that defects and fronts injected by the side wall into the bulk may play an important role [11]. Laveder *et al.* demonstrated that additive white noise intended to mimic the effect of wall defects decreases ν to the value of ν_{eff} measured experimentally provided that the noise level is sufficiently large [20]. Recent unpublished experiments in our group using a sample with a radially ramped spacing [21,22] render the side-wall-injected defect idea an unlikely explanation. On the basis of a numerical simulation using a SH equation Cross *et al.* proposed that the finite size of the experimental convection sample decreases the effective value of ν [23].

Experimental determinations of a characteristic length scale $\overline{\xi}$ usually are based on numerical estimates of the variance σ^2 of the SF, with $\overline{\xi}=1/\sigma$ [9,24]. This is so because the precise analytic form of S(k) is not known in the nonlinear regime above the onset. In Sec. II we examine the relationship between $\overline{\xi}$ and the length ξ that appears explicitly in various functional forms that might be used as approxima-

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FIG. 1. All images are for $\Omega = 17.7$ and $\varepsilon = 0.05$. Upper left: shadowgraph image of size $60d \times 60d$ from $\Gamma = 61.5$. A movie is available [12]. Upper right: shadowgraph image of size $44d \times 44d$ from $\Gamma = 36$. Lower left: the average SF $S(k_x, k_y)$ computed using the FT method and a Kaiser-Bessel window with $\alpha = 2.5$ and averaged over 4096 images like the one in the upper left. Lower right: the average SF from same data as shown in lower left, except $S(k_x, k_y)$ was computed with the MEM.

tions to the SF. We find that $\overline{\xi} \sim \xi^{1/2}$ when ξ is the length appearing in the SF of the linear GL or SH equation. Thus, in these cases $\overline{\xi}$ does not have the same ε dependence as ξ . However, we find that $\overline{\xi} \sim \xi$ for the square of the linear SH SF and for a Gaussian form for the SF. These results suggest that the success of the moment method of data analysis depends upon the rate at which the SF decreases at large k. We also point out that the precise choice of integration limits for the numerical computation of the moments may affect ν_{eff} .

In Sec. III we discuss two methods of determining the SF from patterns. The standard method, using the Fourier power spectrum, is sensitive to the limited size of the experimental images. We distinguish between finite sample-size effects due to the lateral boundaries that were discussed in Ref. [23], and finite image-size effects that would prevail even if a small image were extracted from a central region of a much larger sample. We claim that we must overcome the latter in order to properly measure ν . To accomplish this we also employed the maximum entropy method (MEM), which is discussed in detail in that section. The benefits of the MEM are exhibited through an analysis of images from a SH simulation detailed in Sec. IV. We find that the MEM is quite powerful in its ability to overcome the finite image-size problem.

In Sec. V we present experimental results for patterns in the domain-chaos state. We compare results from the Fourier analysis to the results from the MEM. We determined ξ by fitting several possible functional forms for the SF to the data and found that the results for ξ are not very sensitive to the form of the fitting function. In the case of the Fourier analysis, the fits did not change the result [9] $\nu \simeq \frac{1}{4}$ that had been found before by the moment method. The reason why the moment method also gave this result can be found in the choice of integration limits, which depended on ξ in a way that canceled out the $\xi \sim \sqrt{\xi}$ prediction from integrating the SH SF. In the case of the MEM, we found that $\nu \simeq \frac{1}{2}$ as expected. This indicates that the findings from the Fourier analysis are dominated by the finite image-size effect.

We also examined the maximum height *B* of the SF and found $B \sim \varepsilon^{\beta}$ with $\beta \simeq \frac{3}{4}$ in the case of the Fourier analysis. The two results $\nu \simeq \frac{1}{4}$ and $\beta \simeq \frac{3}{4}$ conspire to retain the expected dependence of the total power on $\varepsilon^{\nu+\beta}$ with $\nu+\beta=1$ even though both ν and β do not have the expected value $\frac{1}{2}$. Once again, we find that the MEM overcomes the finite data length yielding $\beta \simeq \frac{1}{2}$. We also find that the result for ν and β are not strongly dependent on Ω for either the Fourier analysis or the MEM. Thus, we conclude that, in light of careful analysis using the MEM, the experimental domain-chaos state does possess a length scale that is consistent with the prediction from the GL model.

Finally, in Sec. VI, we examine the extent to which the SF can be represented by a unique scaling function over a range of ε and k. We obtain excellent collapse of the data, both in the case of Fourier analysis and the MEM, when the results for ξ obtained from a fit to the SF at each ε are used to scale the SF.

II. MOMENTS OF ANALYTIC FUNCTIONS

In order to better understand the consequences of using numerical moments to compute the correlation length, we derived analytic expressions for the zeroth, first, and second moments of several proposed forms of the SF. This yielded results for the correlation length $\overline{\xi}$ based on moments that could be compared with the correlation length ξ that appears directly in the functional form chosen for the SF. We found that $\overline{\xi} \sim \xi^m$, where *m* depended on the particular form of the SF. This suggests that using moments to measure the correlation length does not necessarily yield $\overline{\xi}$ with the ε dependence implied by the GL model.

We investigated four particular forms of the SF. The exact form for domain chaos is not known. For our purposes one useful form is the SF of the linear SH equation

$$S(k) = \frac{4k_0^2 B}{\xi^2 (k^2 - k_0^2)^2 + 4k_0^2}.$$
 (1)

It is an excellent approximation to the SF of the linearized full equations of motion (the Boussinesq equations) in the presence of additive noise for RBC below the onset [25]. Another useful form is the squared SH SF DOMAIN CHAOS PUZZLE AND THE CALCULATION OF ...

$$S(k) = \left[\frac{4k_0^2\sqrt{B}}{\xi_s^2(k^2 - k_0^2)^2 + 4k_0^2}\right]^2$$
(2)

used by some authors for fits to numerical results in order to estimate a half-width at half-height δk of the distribution [26,27]. In the limit of large ξ , the correlation length ξ in Eq. (1) approaches $1/\delta k$, but ξ_s in Eq. (2) approaches $\sqrt{\sqrt{2}-1}/\delta k$ for large ξ_s . When we directly compare ξ and ξ_s , as in Fig. 14 below, we divide ξ_s by $\sqrt{\sqrt{2}-1}$ so that it approaches $1/\delta k$.

We also considered a Gaussian form

$$S(k) = B \exp[-(\ln 2)(k - k_0)^2 \xi^2]$$
(3)

and a Lorentzian form

$$S(k) = \frac{B}{\xi^2 (k - k_0)^2 + 1}.$$
(4)

The latter is the SF of the one-dimensional linearized GL equation. The correlation length ξ of both the Gaussian and the Lorentzian is exactly equal to $1/\delta k$ regardless of the size of ξ . For all four of these functions we note that the position of the peak of S(k) is at k_0 and $S(k_0)=B$.

The total power is $P = 2\pi \int_0^\infty S(k)k \, dk$. In the case of the SH form

$$P = \frac{2\pi k_0 B}{\xi} \left[\frac{\pi}{2} - \tan^{-1} \left(-\frac{\xi k_0}{2} \right) \right]$$
(5)

which reduces to

$$P = \frac{2\pi^2 k_0 B}{\xi} \left[1 - \frac{2}{\pi \xi k_0} + O\left(\frac{1}{\xi^3}\right) \right]$$
(6)

in the limit of large ξ . In the case of the squared SH form

$$P = 2\pi k_0^2 B \left\{ \frac{1}{4 + \xi_s^2 k_0^2} + \frac{1}{2\xi_s k_0} \left[\frac{\pi}{2} - \tan^{-1} \left(-\frac{\xi_s k_0}{2} \right) \right] \right\}$$
(7)

which reduces to

$$P = \frac{\pi^2 k_0 B}{\xi_s} \left[1 + O\left(\frac{1}{\xi_s^3}\right) \right] \tag{8}$$

in the limit of large ξ_s . The first moment is $\overline{k} = (2\pi/P) \int_0^\infty S(k) k^2 dk$.

In the case of the SH form

$$\bar{k} = k_0 \frac{\frac{2}{\xi k_0} \sin\left[\frac{1}{2} \tan^{-1}\left(\frac{2}{\xi k_0}\right)\right] + \cos\left[\frac{1}{2} \tan^{-1}\left(\frac{2}{\xi k_0}\right)\right]}{\left(1 + \frac{4}{\xi^2 k_0^2}\right)^{1/4} \left[\frac{1}{2} - \frac{1}{\pi} \tan^{-1}\left(-\frac{\xi k_0}{2}\right)\right]}$$
(9)

which reduces to

$$\overline{k} = k_0 \left[1 + \frac{2}{\pi \xi k_0} + O\left(\frac{1}{\xi^2}\right) \right]$$
(10)

in the limit of large ξ .

In the case of the squared SH form

$$\overline{k} = k_0 \frac{\pi \sin\left[\frac{1}{2} \tan^{-1}\left(\frac{2}{\xi_s k_0}\right)\right] + \pi \xi_s k_0 \cos\left[\frac{1}{2} \tan^{-1}\left(\frac{2}{\xi_s k_0}\right)\right]}{2\xi_s^2 k_0^2 \left(1 + \frac{4}{\xi_s^2 k_0^2}\right)^{1/4} \left\{\frac{1}{4 + \xi_s^2 k_0^2} + \frac{1}{2\xi_s k_0} \left[\frac{\pi}{2} - \tan^{-1}\left(-\frac{\xi_s k_0}{2}\right)\right]\right\}}$$
(11)

which reduces to

$$\bar{k} = k_0 \left[1 - \frac{1}{2\xi_s^2 k_0^2} + O\left(\frac{1}{\xi_s^3}\right) \right]$$
(12)

 $\overline{k^{2}} = k_{0}^{2} \frac{\frac{1}{\xi_{s}^{2}k_{0}^{2}} + \frac{1}{2\xi_{s}k_{0}} \left[\frac{\pi}{2} - \tan^{-1}\left(-\frac{\xi_{s}k_{0}}{2}\right)\right]}{\frac{1}{4 + \xi_{s}^{2}k_{0}^{2}} + \frac{1}{2\xi_{s}k_{0}} \left[\frac{\pi}{2} - \tan^{-1}\left(-\frac{\xi_{s}k_{0}}{2}\right)\right]}$ (13)

and Eq. (11) gives \bar{k}^2 . For large ξ_s ,

$$\sigma^{2} = \frac{1}{\xi_{s}^{2}} \left[1 - \frac{8}{3\pi\xi_{s}k_{0}} + O\left(\frac{1}{\xi_{s}^{2}}\right) \right]$$
(14)

in the limit of large ξ_s .

The second moment does not converge for the SH form but it does for the squared SH form. In the case of squared SH, $\sigma^2 \equiv \overline{k^2} - \overline{k}^2$, where

so that $\overline{\xi}_s \sim \xi_s$.

In order to compute a similar expression for the SH form, we introduced a cutoff k_C so that the second moment remained finite. In that case $\sigma^2 = 2\pi P^{-1} \int_0^{k_C} S(k) k^3 dk - \overline{k}^2$ so that

$$\sigma^{2} = \frac{k_{0}^{2} \left\{ \tan^{-1} \left(\frac{\xi}{2k_{0}} [k_{C}^{2} - k_{0}^{2}] \right) + \tan^{-1} \left(\frac{\xi k_{0}}{2} \right) \right\} + \frac{k_{0}}{\xi} \ln \left(\frac{4k_{0}^{2} + \xi^{2} [k_{C}^{2} - k_{0}^{2}]^{2}}{4k_{0}^{2} + \xi^{2} k_{0}^{4}} \right)}{\tan^{-1} \left(\frac{\xi k_{C}^{2}}{2k_{0}} - \frac{\xi k_{0}}{2} \right) - \tan^{-1} \left(- \frac{\xi k_{0}}{2} \right)} - \bar{k}^{2}$$
(15)

and in the limit of large ξ

$$\sigma^{2} \simeq \frac{1}{\xi} \left[\frac{k_{0}}{\pi} \ln \left(\frac{[k_{C}^{2} - k_{0}^{2}]^{2}}{k_{0}^{4}} \right) - \frac{4k_{0}}{\pi} \right] + O\left(\frac{1}{\xi^{2}} \right).$$
(16)

Equation (16) indicates that in the case of the SH form $\xi \sim \sqrt{\xi}$ regardless of the cutoff k_C . Although we do not present the details here, we also found that $\overline{\xi} \sim \sqrt{\xi}$ for the Lorentzian form but $\overline{\xi} \sim \xi$ for the Gaussian form.

Figure 2 compares results for ξ from the numerical integration of the SH SF and the squared SH SF with the analytic results detailed above. The lowest order expansion for the squared SH SF in Eq. (14) is an excellent approximation to the exact result as it lands almost directly on top of it. However, although the exponent is $-\frac{1}{2}$, it does give a $\overline{\xi}_s$ that is smaller than the input ξ (shown as the solid line in Fig. 2) because of the extra constant $\sqrt{\sqrt{2}-1}$ discussed earlier. The approximate result for the SH SF [from Eq. (16)] is not very close to the exact result [from Eq. (15)] because the exact result for \overline{k} [Eq. (9)] was used to compute Eq. (16) while the dashed curve shown in Fig. 2 was computed with a finite



FIG. 2. $\overline{\xi}$ computed from the integration of the SH SF and the squared SH SF. The analytic results were evaluated with $\xi = 1.6\varepsilon^{-1/2}$, $k = \pi$, and $k_C = 14$. Solid line: $\xi = 1.6\varepsilon^{-1/2}$ (chosen to match the solid line in Fig. 16). Dashed line: $\overline{\xi}$ from SH computed with Eq. (15) using $k_C = 14$ and computing \overline{k} numerically so that the integration is done only over the range 0 < k < 14 for consistency. Dashed-dotted line: $\overline{\xi}_s$ computed from Eqs. (11) and (13). Thin solid line that passes almost directly through dotted line: Approximate $\overline{\xi}_s$ from SH computed $\overline{\xi}_s$ from squared SH computed from Eq. (14).

cutoff for \overline{k} to match the cutoff used in the integral for $\overline{k^2}$ for the sake of consistency. Nevertheless, the approximate result is parallel to the exact result with the cutoff indicating that regardless of these details, the exponent from integrating the SH SF is $-\frac{1}{4}$.

When using numerical moments to compute ν_{eff} from the experimental data, the choice of the limits for the integration clouds the results shown in Fig. 2. If constant limits are chosen then the results in Fig. 2 apply, and the measured exponent is affected by the underlying shape of S(k). However in some previous experimental measurements, the limits k_{\pm} were chosen such that $S(k_{\pm}) = \gamma S(k_0)$, where $\gamma = 0.15$ [9,28]. Applying this relation to the SH SF reveals that k_{\pm} is ξ dependent:

$$k_{\pm} = \sqrt{k_0^2 \pm \frac{2k_0}{\xi} \sqrt{\frac{1-\gamma}{\gamma}}}.$$
 (17)

Numerically evaluating $\overline{\xi}$ for the SH SF over the range $k_- < k < k_+$ using the data for ξ shown in the solid line in Fig. 2 yields a $\overline{\xi}$ that lands almost exactly on top of the solid line. This is particularly problematic because it implies that ξ -dependent limits artificially modify the ε dependence of the variance. In this case, the special choice of limits given by Eq. (17) effectively overcame the ξ dependence predicted by Eq. (16).

According to the GL model, at small ε one expects $\xi \sim \varepsilon^{-\nu}$ with $\nu = \frac{1}{2}$ [16,17]. One also expects the total power to vanish at the onset in proportion to ε . Thus, if Eq. (1) or Eq. (2) gives the shape of S(k) correctly, then according to Eq. (6) or Eq. (8), $P \sim \varepsilon^{\nu+\beta}$ with $\nu+\beta=1$ and $B \sim \varepsilon^{\beta}$ with $\beta = \frac{1}{2}$.

III. ESTIMATION OF S(k) FROM PATTERN IMAGES

We found that the accuracy of S(k), estimated from the Fourier power spectrum, suffered greatly due to the finite size of the images of patterns that are available from experiment. In applying the Fourier-transform (FT) method to compute S(k) from experimental data, we divided the images by a reference image taken below the onset, applied a Kaiser-Bessel window [29] to the divided images, and computed the magnitude squared of the FT. The azimuthal average of the squared magnitude of the FT yielded the SF S(k).

We experimented with three windowing functions: a square window, a Welch window, and a Kaiser-Bessel window [29]

$$w_{KB}(t) = \begin{cases} I_0(\pi \alpha \sqrt{1 - [t/\tau]^2}) / I_0(\pi \alpha), & |t| < \tau \\ 0, & |t| > \tau. \end{cases}$$
(18)

In Eq. (18), t is the distance along one of the axes from the center, τ is the half-width of the image, and I_0 is the modified Bessel function of the first kind and order zero. The parameter α controls the rate at which the window drops off as the edge of the image is approached. Since the data were two dimensional, the window was the product of a one-dimensional window function in each direction. Since the windowing function attenuates the signal around the edges of the image, it reduces the total power. To compensate for this we divided S(k) by a constant so that the total power in the final SF agreed with the total power of the raw image.

The specific windowing function did not greatly affect the result for ξ . We ultimately settled on using a Kaiser-Bessel window with α =2.5 for the results given in this paper. Our major results, namely the exponents ν and β and the scaling collapse of the SF, were independent of the windowing function.

We used a fast Fourier-transform (FFT) algorithm [30] capable of transforming images of arbitrary size to compute the SF so that no interpolation or zero padding was required to resize the image to an integer power of 2. We found that interpolation distorts the large-k behavior of the SF because it smooths out random noise that is present in the original signal. The use of zero padding circumvents the smoothing of the noise and thus avoids this distortion at large k, but instead inserts ringing at small k. Due to the easy availability of FFT algorithms that can work on any size image and the speed of modern computers, there is no reason to sacrifice the behavior of the SF at either large or small k. A minor tradeoff is that previous work utilized an aspect-ratio correction to the image that removed a slight anisotropy in the frame grabber [28]. Because this correction requires interpolation of the raw image we avoided using it. We expected only a very slight error by doing so because the raw images are nearly square. However, in the Γ =36 sample there was a radial distortion, due to an optical aberration, that was strong enough to warrant its removal in order to avoid a systematic error in the length scale. We did not investigate the large-kbehavior in that sample, so we expect no significant problem from the distortion correction.

Even after dividing the experimental images by an optical background, the resulting SF still contained the nondeterministic part of the background spectrum present in the images taken below the onset. Since fluctuations [31,32] are too feeble to be detected for the parameters of the present experiment, we attributed this background signal primarily to electronic noise and subtracted a background, determined below the onset, from the SF above the onset. As a result, for the case of experimental data, the analysis that follows is applied to the background subtracted SF $\delta S(k) \equiv S(k) - S_b(k)$, where $S_b(k)$ is the SF averaged over many images below the onset. We also applied the FT to simulations of the SH domain-chaos model. In that case there was no need to divide by a reference image or to subtract the electronic

noise, so we used S(k) computed directly from the simulation images.

We attempted to overcome the finite image-size problem of the FT method by using the MEM to estimate S(k). Although this method is commonly used for one-dimensional (1D) data [33], computing the spectrum of 2D data with this technique is still somewhat of an open problem [34]. We implemented the algorithm detailed in Ref. [35] which uses an iterative method to arrive at the power-spectrum estimate. Figure 4 in Ref. [35] provides a detailed flowchart of the MEM algorithm, which we followed precisely.

The reason why we used the MEM to overcome the finite image size is because the MEM seeks to continue the autocorrelation of the image beyond the available data length. The MEM has the property that it continues the autocorrelation such that the integral of the logarithm of the continued power spectrum (the spectral entropy) is maximized subject to the constraint that the FT of the continued spectrum still matches the autocorrelation of the available data over its range, i.e., the Wiener-Khinchin theorem is satisfied over the known range [34]. However, we do not claim that the entropy maximization is directly the reason for the success of the MEM. Rather, the MEM is simply a method of expressing the power spectrum as a series expansion, just like the FT is, but it uses a series of a different form that is very useful for our purpose. The MEM provides the power spectrum as an expansion of the form

$$S(k_x, k_y) = \frac{1}{F[\lambda(n_1, n_2)]},$$
(19)

where $\lambda(n_1, n_2)$ are the coefficients of the expansion and $F[\cdots]$ is the discrete Fourier transform from (n_1, n_2) space to (k_x, k_y) space. This is an expansion containing sines and cosines in the denominator, in contrast with the FT where sines and cosines are in the numerator, thus the resulting power spectrum may more accurately represent sharp peaks because it may contain poles [33]. The property that the MEM continues the autocorrelation beyond the data range is valuable as well. It was shown previously [36] that the MEM is much less sensitive to short data lengths than the standard Fourier analysis.

The algorithm in Ref. [35] depends on an accurate estimate of the autocorrelation of the data. A central section is cut from the autocorrelation data and used in the iterative process. For all the analysis in the present work we used a region size of 45×45 data points, which corresponded to about $12d \times 12d$ for the Γ =61.5 sample and also for the SH simulation. The iterative process produces autocorrelation data that is continued beyond this region according to the spectral-entropy maximization criteria that defines the MEM. The number of coefficients $\lambda(n_1, n_2)$ determines the size of the continued region. In principle, it is possible to use a relatively small continued-region size, in order to reduce the required amount of computation, and then embed the resulting $\lambda(n_1, n_2)$ into a larger region, setting higher order coefficients to zero in order to produce a finely meshed power spectrum. In practice, we found that this approach, while advocated in Ref. [35], did not always produce positive-

TABLE I. Convergence test for SH simulation data with $\Gamma^* \!=\! 150.$

ϵ_0	ν	β
10 ⁻³	0.858	0.277
10 ⁻⁴	0.619	0.455
10 ⁻⁵	0.555	0.496
10-6	0.533	0.506

definite power spectra and thus was not stable for our purposes. Instead we ran the entire algorithm on a large 720 \times 720 mesh for $\lambda(n_1, n_2)$. Although this was heavily computation intensive, it did provide a reliable power spectrum estimate after a sufficient number of iterations. On our modest fleet of 2 GHz PowerMac G5s, we could run roughly 200 iterations per minute per CPU. Typically we needed 50 000 to 1 million iterations for convergence, depending on the ε step, making the processing of all the data in the present work a fairly massive undertaking.

The number of iterations depended on the autocorrelation error ϵ_0 , as defined by Eq. (25) in Ref. [35], which was reduced to a specified level. In the case of the SH simulation data discussed in Sec. IV, we found that $\epsilon_0 = 10^{-5}$ was sufficiently small to give convergence of the SF. Table I shows the results for ν and β in the convergence test. By $\epsilon_0 = 10^{-5}$, ν and β have nearly reached a constant. In the case of the experimental data discussed in Sec. V, we found that we only needed $\epsilon_0 = 10^{-3}$ for satisfactory convergence. This is likely due to the better statistics for the autocorrelation function in the case of the experiment due to the fact that we averaged the autocorrelation function over 4096 images per ε step in the experiment, but only 256 images per ε step in the simulation.

In utilizing the MEM, we first averaged the autocorrelation over many images in order to reduce statistical fluctuations. Then the MEM was applied to this averaged autocorrelation to yield a single estimate of $S(k_x, k_y)$ at each ε step. We note that, because the FT is linear, this is analogous to the procedure used in the FT method where we reversed the order of operations by computing the SF for each individual image and then averaging those to yield a single SF at each ε step. Due to the iterative nature of the MEM algorithm we used, it was prohibitively slow to compute the SF for each image individually.

We used the SF to determine the correlation length. However, we modified the analysis scheme compared to earlier work [9,24], in light of the results presented in Sec. II, to avoid using numerical moments. We determined ξ by fitting each of the functions in Eqs. (1)–(4), multiplied by the shadowgraph transfer function from Refs. [37,38], to the data near the peak of the SF averaged over all images at a particular ε .

IV. FINITE IMAGE-SIZE EFFECT IN SIMULATION OF SH MODEL FOR DOMAIN CHAOS

The finite size of the pattern images has a significant impact on the accuracy of a measurement of ξ from S(k). To



FIG. 3. A solution of Eq. (20) for $\tilde{\epsilon}=0.12$. This is a 512×512 ($\Gamma^*=150$) cutout from the center of a 1024×1024 image with $\Gamma^*=300$. A movie is available [40].

study this effect, we ran simulations using the Swift-Hohenberg model for domain chaos [17]. We utilized the algorithm in Ref. [17] and periodic boundary conditions to solve the equation

$$\partial_t \psi = \tilde{\varepsilon} \psi - (\nabla^2 + 1)^2 \psi - g_1 \psi^3 + g_2 \hat{z} \cdot \nabla \times [(\nabla \psi)^2 \nabla \psi] + g_3 \nabla \cdot [(\nabla \psi)^2 \nabla \psi]$$
(20)

for ψ , a field that can be used to model the temperature of the convection sample at the midplane. Figure 3 shows an example of ψ . The time step for the numerical integration was 0.1. The initial condition for ψ was a random grid of straightroll patches. At each $\tilde{\varepsilon}$, 10 000 warmup time steps were performed followed by 256 snapshots of ψ recorded at an interval of 1250 time steps. The pixel spacing was chosen to reflect a nonunity sample thickness, unlike the choice in Ref. [17], in order for the wave number and ξ to be nearer to the values in the experiment. The choice of this constant has no effect on the value of ν or β , thus it does not affect our main conclusions.

The control parameter in the simulation is related to the experimental control parameter by $\tilde{\varepsilon} = (4/k_c^2 \xi_0^2)\varepsilon = 2.60\varepsilon$ [1], where k_c is the critical wave number and ξ_0 is the curvature of the neutral curve [39]. The numerical value 2.60 corresponds to $\Omega = 17.5$. Figure 4 shows both ξ_0^2 and $4/k_c^2 \xi_0^2$ as a function of Ω as computed numerically from the neutral curve. We note that the exact value of $4/k_c^2 \xi_0^2$ has no effect on the values for ξ , B, ν , or β at a given $\tilde{\varepsilon}$, and only serves to adjust the value of ε by a constant factor.

The parameters g_1 , g_2 , and g_3 control the stability balloon and can be chosen to model a specific Ω and Küppers-Lortz angle θ_{KL} . In the present work we used $g_1=1$, $g_2=-2.4534$, and $g_3=0.522$ which are the same parameters used in Fig. 1(b) of Ref. [17] and which correspond to $\theta_{KL}=51^{\circ}$ and roughly $\Omega \simeq 17.5$ for the Prandtl number in the present experiment. Note that Eq. (20) assumes an infinite Prandtl



FIG. 4. Top figure: curvature ξ_0^2 of the neutral curve. Bottom figure: $4/k_c^2 \xi_0^2$.

number, so this rough value of Ω comes from comparing Ω/Ω_c , where Ω_c is Prandtl number dependent.

As a check on the accuracy of our implementation of the solver algorithm we attempted to reproduce Fig. 7(a) of Ref. [17]. Our simulation agreed within 2% for the data points at $\tilde{\varepsilon}$ =0.1, 0.2, and 0.3 in that figure, but differed by about 27% for the data point at $\tilde{\varepsilon}$ =0.03 for an unknown reason. Nevertheless, we are confident in the correctness of our simulation and in the results to follow.

In order to determine the effect of the finite image size on the measured value of ξ we ran simulations of image size 1024×1024 corresponding to an image aspect ratio $\Gamma^*=300$, where Γ^* refers to the horizontal width of the image. This is in contrast to the aspect ratio Γ which refers to the physical aspect ratio of the convection sample. From these large simulations we cut various sized center sections and computed the SF using both the FT and the MEM following the procedure described in Sec. III. We fit the SH function and the squared SH function to the SF.

The choice of $\overline{\Gamma}^*$ strongly affected the shape of the SF when computed with the FT. Figure 5 compares the SF of the same data for two different values of Γ^* . The same data analyzed with the MEM, as shown in Fig. 6, are affected slightly by Γ^* , but it is not nearly as sensitive as the FT. It is important to note that the sharpest SF peak is not necessarily the best. The $\Gamma^*=300$ SF from the FT is sharper than either of the MEM peaks, but it is not at all consistent with its shorter data length relative, $\Gamma^*=75$. In contrast, the MEM SFs land nearly on top of each other when comparing $\Gamma^*=300$ and $\Gamma^*=75$. The ability to accurately represent the



FIG. 5. Structure factor (SF) from simulations using Eq. (20) with $\tilde{\epsilon}$ =0.12, computed with the Fourier-transform method. Both data sets are from the same simulation except with a different size center cutout used to compute the SF. Triangles: Γ^* =300. Circles: Γ^* =75. Solid lines: Fits of Eq. (1) to the data over the range $k\pm 3/\xi$.

SF peak for relatively small image sizes is crucial because system sizes as large as $\Gamma^*=300$ are experimentally inaccessible.

From fitting the SF for both the FT and MEM, we computed ξ for many ε and Γ^* as shown in Fig. 7. Once again we found that the MEM provides significantly more consistent results for vastly different Γ^* . In the case of the FT results, it is critical to note that increasing Γ^* does not simply increase ξ due to the larger data length. It also increases the slope of ξ vs ε on a logarithmic graph, thus affecting the measured ν . Since we wish to measure ν accurately enough to compare with the model prediction $\nu = \frac{1}{2}$, this is a discouraging outcome.

We ascertained the effect of image size on the accuracy of ν by computing ν as a function of Γ^* as shown in Fig. 8. The two lowest Γ^* points in that figure correspond to the available image size in the experimental samples discussed in the present work. The ν values from the MEM and FT method



FIG. 6. Structure factor (SF) from simulations using Eq. (20) with $\tilde{\varepsilon}$ =0.12, computed with the maximum entropy method (MEM). Both data sets are from the same simulation except with a different size center cutout used to compute the SF. Triangles: Γ^* =300. Circles: Γ^* =75. Solid lines: Fits of Eq. (1) to the data over the range $k\pm 3/\xi$.



FIG. 7. Measurements of ξ from fits of Eq. (1) to many SFs like those shown in Figs. 5 and 6. Open symbols: from the FT method. Solid symbols: from the MEM. Triangles: $\Gamma^*=300$. Circles: $\Gamma^*=75$. Solid lines: Fits of the power law $\xi \propto \varepsilon^{-\nu}$ to the data over the range shown.

both approached nearly the same asymptotic value at large Γ^* . Fortunately, the result from the MEM has nearly reached this asymptote at even the smallest Γ^* indicating that it may be reliably used for measuring ν even in the case of small images. Not only is the FT measurement of ν much too low at the smallest Γ^* , but it also contains rather large fluctuations at those values. At the largest Γ^* it is almost as good as the MEM, but that does not help for the analysis of experiments which are limited roughly to $\Gamma^* < 100$ [41].

We observed a similar finite image-size effect for the scaling of *B* with ε . As discussed in Sec. II we expect that $B \sim \varepsilon^{1/2}$ provided that ξ obeys the scaling in the amplitude model, i.e., $\xi \sim \varepsilon^{-1/2}$. Our SF fits that yielded ξ also gave *B*. Figure 9 shows some examples of *B* for the same data as shown in Fig. 7.

We extracted a scaling exponent β by fitting the equation $B \propto \varepsilon^{\beta}$ to the data. As indicated by Fig. 10, the result is simi-



FIG. 8. Results for ν from fits like those shown in Fig. 7. Solid symbols: from the MEM. Open symbols: from the FT method. Circles: ξ was determined by fitting the SH SF Eq. (1) to the data. Squares: ξ was determined by fitting a squared SH SF Eq. (2) to the data. Dashed line: the $\nu = \frac{1}{2}$ prediction from model equations.



FIG. 9. Results for *B* from fits of Eq. (1) to many SFs like those shown in Figs. 5 and 6. Open symbols: from the FT method. Solid symbols: from the MEM. Triangles: $\Gamma^*=300$. Circles: $\Gamma^*=75$. Solid lines: Fits of the power law $B \propto \varepsilon^{\beta}$ to the data over the same range as shown in Fig. 7.

lar to the finite image-size effect on ν . At the smallest Γ^* values, the MEM results exhibit a slight Γ^* dependence, but they quickly reach a nearly constant value as Γ^* increases. The FT method suffers from a strong Γ^* dependence. However, it is quite satisfying that for Γ^* near the experimental values, we obtained $\nu \approx 0.25$ and $\beta \approx 0.75$ from the FT method, in agreement with what we (and others previously) observed in the experiment.

Figure 11 shows the results for $\nu + \beta$ for both the MEM and the FT method. Both are close to the expected result $\nu + \beta = 1$, and approach it even more closely as Γ^* increases.

V. EXPERIMENTAL MEASUREMENTS

We acquired new data using an apparatus described previously [37]. There were two samples which both used com-



FIG. 10. Results for β from fits like those shown in Fig. 9. Solid symbols: from the MEM. Open symbols: from the FT method. Circles: ξ was determined by fitting the SH SF Eq. (1) to the data. Squares: ξ was determined by fitting the squared SH SF Eq. (2) to the data. Dashed line: the $\beta = \frac{1}{2}$ prediction from model equations.



FIG. 11. Values of $\nu + \beta$ from combining the results shown in Figs. 8 and 10. Solid symbols: from the MEM. Open symbols: from the FT method. Circles: ξ and *B* determined by fitting the SH SF Eq. (1) to the SFs. Squares: ξ and *B* determined by fitting the squared SH SF Eq. (2) to the SFs. Dashed line: $\nu + \beta = 1$.

pressed SF₆ gas. The primary sample was at a pressure of 20.00 bars and mean temperature of 38.00 °C, where the Prandtl number $\eta/(\rho\kappa)$ (κ is the thermal diffusivity) was 0.87. The aspect ratio $\Gamma \equiv D/(2d)$ (*D* is the sample diameter) was 61.5. A secondary sample with Γ =36, which is discussed briefly in this work, was pressurized at 12.34 bars with a mean temperature of 38.00 °C and the Prandtl number was 0.82.

We determined ξ by fitting each of the functions in Eqs. (1)–(4), multiplied by the shadowgraph transfer function from Refs. [37,38], to the data near the peak of the SF. Typically we used a range $k_0 \pm 3/\xi$ where the initial guess of ξ and k_0 for the fitting range was estimated by Eq. (6) using the zeroth numerical moment, peak value, and peak position. The fit was not very sensitive to the range of k provided that the range included a sufficient number of points. Figure 12 shows that for the FT method, all of the functions provide a good fit near the half height, where ξ is determined, and near



FIG. 12. Fits of Eqs. (1)–(4) to the experimental SF computed with the FT for Ω =17.7 and ε =0.05. Solid line: fit of SH SF Eq. (1). Dashed line: fit of squared SH SF Eq. (2). Dashed-dotted line: fit of Gaussian SF Eq. (3). Dotted line: fit of Lorentzian SF Eq. (4). All fitting functions are multiplied by the shadowgraph transfer function.



FIG. 13. Fits of Eqs. (1)–(4) to the experimental SF computed with the MEM for Ω =17.7 and ε =0.05. Top figure: linear-linear plot. Bottom figure: log-linear plot. Solid line: fit of SH SF Eq. (1). Dashed line: fit of squared SH SF Eq. (2). Dashed-dotted line: fit of Gaussian SF Eq. (3). Dotted line: fit of Lorentzian SF Eq. (4). All fitting functions are multiplied by the shadowgraph transfer function.

the peak where the fits give the value of *B*. Figure 13 shows similarly good fitting results for the SF estimated with the MEM.

Figure 14 shows the effect of the fitting function on the dependence of ξ on ε for Ω =17.7. Although each of the fitting functions gave slightly different values for ξ , all of them gave nearly the same value for ν , with $\nu \approx 0.25$ from the FT method and $\nu \approx 0.5$ from the MEM. This suggests that the function fitting is a robust method for measuring ξ because knowledge of the exact functional form of the SF is not required to yield a consistent measurement for ξ . In spite of this consistency for ν , we concluded that some fitting functions are better than others as will be seen below.

The results from the MEM are in much better agreement than the results from the FT method, with the prediction $\nu = \frac{1}{2}$ from the GL model. This difference is even more dramatic when considering a smaller-sized cutout region from the data. Figure 15 shows ξ for two different Γ , where the analysis has been applied to a central region of identical size in either case. Although in the case of $\Gamma = 61.5$ the data shown in Fig. 15 are from the same raw data as shown in Fig. 14, the FT method gives a somewhat smaller value of ν because of the reduced image size of the smaller cutout region. The MEM also suffers some minor decrease in the value of ν , as this cutout size corresponds to the smallest Γ^* data point in Fig. 8. Although only barely noticeable in the



FIG. 14. Measurements of ξ by fitting Eqs. (1)–(4) to the experimental SF for Ω =17.7. Open symbols: SF was computed using a Kaiser-Bessel window with α =2.5. Solid symbols: SF was computed with the MEM. Dashed line: $\varepsilon^{-1/4}$. Solid line: $\varepsilon^{-1/2}$. Circles: ξ from a fitting of SH SF. Squares: ξ from a fitting of squared SH SF. Diamonds: ξ from fitting of Gaussian SF. Triangles: ξ from fitting of Lorentzian SF.

FT result, the MEM clearly shows that ξ is larger in the case of Γ =36 as compared to Γ =61.5. A likely explanation is the increased influence of the centrifugal force in the larger sample. The presence of the centrifugal force has been shown to decrease the domain size [41].

The diminishing slope at very small ε shown in Figs. 14 and 15 may be indicative of a physical finite-size effect [23] due to the lateral boundary of the experimental samples. However, over the range of fitting shown in Fig. 15, no such effect is observed. As a comparison with the result in Fig. 3 of Ref. [23], Fig. 16 shows a plot of $\varepsilon^{-1/2}$ scaled with ξ against $\varepsilon^{-1/2}$ scaled with Γ . The data are roughly constant over the range of ε indicating consistency with the GL prediction for ν . Unfortunately the data from two different



FIG. 15. Comparison of ξ for $\Omega = 17.7$ and both $\Gamma = 36$ and $\Gamma = 61.5$, measured with SFs computed from $44d \times 44d$ square cutouts using both the MEM and the FT method. Squares: $\Gamma = 36$. Circles: $\Gamma = 61.5$. Open symbols: FT. Solid symbols: MEM. For $\Gamma = 36$ the fitting range was $0.018 \le \epsilon \le 0.11$; MEM, $\nu = 0.57$; FT, $\nu = 0.17$. For $\Gamma = 61.5$ the fitting range was $0.017 \le \epsilon \le 0.10$; MEM, $\nu = 0.45$; FT, $\nu = 0.15$.



FIG. 16. $\varepsilon^{-1/2}$ scaled against ξ and Γ for $\Omega = 17.7$ and both $\Gamma = 36$ and $\Gamma = 61.5$, measured with SFs computed from $44d \times 44d$ square cutouts using the MEM. Squares: $\Gamma = 36$. Circles: $\Gamma = 61.5$. The data are the same as in Fig. 15 and are shown over the range of the fits in that figure.

 Γ do not collapse onto a single curve as in Ref. [23]. This may be due to the effect of the centrifugal force, which was neglected in that work, but is unavoidable in the present experiment.

Although, in the case of the FT method, the scaling exponent ν did not agree with the GL model, the scaling of the total power agreed for both the FT method and the MEM. Figure 17 shows the total power for Ω =17.7 measured by several methods. The zeroth numerical moment of the data did not perfectly agree with the total power computed from Eqs. (5) or (7) but it was close. In the case of these equations, the fit parameters B, k_0 , and ξ (or ξ_s for the squared SH) were used to calculate P. Since Eqs. (5) and (7) represent the total power over the range $0 < k < \infty$ and the zeroth numerical moment was necessarily computed over a finite range



FIG. 17. Total power for $\Omega = 17.7$ from SFs computed with both the FT method and the MEM and given by various methods. Solid line: ε^1 . Open symbols: from the FT method. Solid symbols: from the MEM. Diamonds: power from the zeroth numerical moment of the SF data integrated over $k_0 - 3/\xi \le k \le k_0 + 3/\xi$. Circles: power given by Eq. (5) using the parameters acquired from fitting the SH SF to the data. Squares: power given by Eq. (7) using the parameters acquired from fitting the squared SH SF to the data.



FIG. 18. *B* determined by fitting the FT experimental SF to the SH function. Solid lines: power-law fits to the data to measure β . Pluses: $\Omega = 15$. Circles: $\Omega = 16.25$. Squares: $\Omega = 17.7$. Triangles: $\Omega = 19.5$. Diamonds: $\Omega = 21.7$.

 $k_0-3/\xi \le k \le k_0+3/\xi$, the slight discrepancy in the total power is not surprising. A numerical integration of Eqs. (1) and (2) over a finite *k* range yields a total power closer to the numerical moment result, however, it is absent from Fig. 17 because it is too close to the other data points to be easily distinguishable. In spite of this minor discrepancy, all three measurements of the total power are proportional to ε as expected.

Since, in the case of the FT method, the dependence of ξ on ε differed from the GL prediction of $\varepsilon^{-1/2}$, it is important to also investigate the dependence of *B* on ε . As shown in Fig. 17, the combination of *B* and ξ according to Eqs. (6) and (8) yielded a total power that depended on ε in the predicted way for both the FT method and the MEM.

Figure 18 shows the result for *B* measured by fitting the SH SF to the experimental SF at all Ω values. The slight variation of the values of β (slopes of the lines in the figure) did not depend systematically on Ω and most likely it is due to experimental error. The power-law fits shown in the figure were over the same range as was used to determine ν in Fig. 19. One sees that *B* alone did not depend on $\varepsilon^{1/2}$ as expected; instead $B \sim \varepsilon^{\beta}$ with, averaging over the results from all Ω , $\beta \approx 0.73$ while the Ω -averaged $\nu \approx 0.25$. In other words, in the case of the FT method, *B* and ξ conspired to produce the expected $P \sim \varepsilon^{\nu+\beta}$ with $\nu+\beta \approx 1$.

Figures 20 and 21 show the analogous results from the MEM. The MEM yielded much more steeply sloped ξ vs ε curves as indicated by Fig. 21. The resulting ν was in much better agreement with the GL model prediction. Likewise, β was much closer to 1/2 than for the FT method. Averaged over Ω , $\nu \approx 0.46$ and $\beta \approx 0.63$ from the MEM. Figure 22 summarizes the behavior of the exponents for both the MEM and the FT method as a function of Ω . The MEM clearly gave the closest result in agreement with the prediction $\nu = \frac{1}{2}$ and also $\beta = \frac{1}{2}$. However, the FT method yielded the best agreement with the prediction $\nu + \beta = 1$, with the MEM not much further off. Considering the results of Sec. IV, the MEM is more reliable. Thus we conclude that the experimental length scale is consistent with the prediction from the GL model.



FIG. 19. ξ determined by fitting the FT experimental SF to the SH function. Solid lines: power-law fits to the data to determine ν . Pluses: Ω =15. Circles: Ω =16.25. Squares: Ω =17.7. Triangles: Ω =19.5. Diamonds: Ω =21.7.

VI. SCALING OF $\delta S(k)$ FOR EXPERIMENTAL DATA AND ANALYTIC FUNCTIONS

The scaling analogy to critical phenomena extends beyond the power-law dependence of ξ and B on ε . In order to more deeply probe this scaling, we rescaled the SFs at different ε in an attempt to collapse them all onto a single curve. We followed the procedure of Ref. [42]. First we normalized the structure factor so that $2\pi \int_0^\infty \delta S(k)k \, dk=1$. In applying this normalization to the experimental data, we evaluated the integral over the range $k_0-3/\xi \le k \le k_0+3/\xi$. This included most of the total power present in the experimental data. Figure 23 shows the MEM results for several ε values and demonstrates that normalization alone is not sufficient to collapse the data onto a unique curve. It is also necessary to rescale the SF on both the abscissa and ordinate axes so that $x \equiv (k-k_0)\xi$ and $\delta \tilde{S}(x) \equiv (k/\xi) \, \delta S(x)$.

Applying this variable transformation to the analytic forms in Eqs. (1)–(4) provides some insight into the effect of



FIG. 20. *B* determined by fitting the MEM experimental SF to the SH function. Solid lines: power-law fits to the data to determine β . Pluses: Ω =15. Circles: Ω =16.25. Squares: Ω =17.7. Triangles: Ω =19.5. Diamonds: Ω =21.7.



FIG. 21. ξ determined by fitting the MEM experimental SF to the SH function. Solid lines: power-law fits to the data to determine ν . Pluses: Ω =15. Circles: Ω =16.25. Squares: Ω =17.7. Triangles: Ω =19.5. Diamonds: Ω =21.7.

rescaling. In the critical-point limit, of $\xi \rightarrow \infty$ and evaluating the integral normalization over the range $0 \le k \le \infty$, all parameters cancel, leaving only a function of *x*. This yields

$$\tilde{S}(x) = \frac{1}{2\pi^2(1+x^2)}$$
(21)

in the case of the SH form,

$$\tilde{S}(x) = \frac{1}{\pi^2 (1+x^2)^2}$$
(22)

in the case of the squared SH form, and

$$\tilde{S}(x) = \frac{\exp(-x^2)}{2\pi^{3/2}}$$
(23)

in the case of the Gaussian form. We refrain from listing the rescaled Lorentzian because the zeroth moment diverges, making it impossible to normalize without introducing a cutoff.



FIG. 22. Exponents from the data shown in Figs. 18–21. Open symbols: from the FT method. Solid symbols: from the MEM. Circles: ν . Squares: β . Diamonds: $\nu + \beta$. Solid line: $\nu = \beta = \frac{1}{2}$ prediction from GL model. Dashed line: $\nu + \beta = 1$.



FIG. 23. The normalized SFs for $\Omega = 17.7$ computed with the MEM. Open circles: $\varepsilon = 0.017$. Solid circles: $\varepsilon = 0.025$. Open triangles: $\varepsilon = 0.033$. Solid triangles: $\varepsilon = 0.05$. Open squares: $\varepsilon = 0.08$. Solid squares: $\varepsilon = 0.10$.

Figure 24 shows the rescaled experimental SFs from the MEM on a linear (top figure) and on a logarithmic (bottom figure) scale. Although not shown, we found comparable results for both the normalized and rescaled SFs computed with the FT method. The figure also includes the rescaled SH



FIG. 24. Scaled SFs for Ω =17.7 computed with the MEM. Top figure: linear-linear plot. Bottom figure: log-linear plot. The symbols are as in Fig. 23. Dotted line: rescaled SH SF Eq. (21). Dashed line: rescaled squared SH SF Eq. (22). Solid line: numerically rescaled SH SF using finite limits for its normalization. Dashed-dotted line: numerically rescaled squared SH SF using finite limits for its normalization.

and squared SH SFs given by Eqs. (21) and (22). We omit the Gaussian form in Eq. (23) in order to maximize the clarity of the figure. It is the poorest empirical representation out of Eqs. (21)–(23), and the least physically justifiable. Note that the curves of Eqs. (21) and (22) are not fits to the experimental data; there are no free parameters for fitting. None of them provide a particularly good scaled representation of the data near the peak. The experimental results fall somewhere between the SH (dotted line) and the squared SH (dashed line) form.

The disagreement between the scaled data and the scaled functions is primarily due to the normalization of the experimental data, which is over a finite range unlike the normalization in Eqs. (21) and (22) which is over all k. Also shown are collapsed forms of Eqs. (1) and (2) computed numerically using the normalization over the same finite range as in the experimental SFs. The numerically computed forms were evaluated at finite ε , instead of taking the limit of $\xi \rightarrow \infty$, as was done in the analytic cases of Eqs. (21)-(23). As a result, ξ and k_0 remained as constants in the collapsed forms. We used the values of ξ and k_0 from the $\varepsilon = 0.10$ data point. This choice barely affected the numerically collapsed curves because $k_0 \xi$ was relatively large for all values of ε shown. These curves provide insight into the agreement of the shape of Eqs. (1) and (2) with the experimental data. The numerically computed SH SF agreed quite well with the collapsed experimental data, while the squared SH SF did not.

VII. SUMMARY AND CONCLUSION

In this paper we carefully examined two methods, the FT method and the MEM [33], for determining critical parameters describing the spatiotemporal chaos state in rotating Rayleigh-Bénard convection known as domain chaos. We found that a correlation length ξ , equal to the inverse halfwidth at half-height of the structure factor S(k), can be determined reliably by fitting one of several trial functions to the experimental data. We examined a Lorentzian, Swift-Hohenberg, squared Swift-Hohenberg, and Gaussian form. We prefer this fitting method over computing numerical moments from the data (as had been done in the past) because we were able to show analytically that the length $\overline{\xi}=1/\sigma$ (σ^2 is the variance of the data) will be proportional to ξ only when S(k) decreases sufficiently fast at large k.

For a technique of estimating the SF, we found that the MEM was much superior to the classic FT method. There is a severe dependence on image size in the case of the FT method that is quite apparent from our analysis of various

sized images from the simulation using the SH domain-chaos model. Since the experimental images are relatively small, the MEM is required in order to accurately determine the SF from the patterns.

We analyzed experimental shadowgraph images of domain chaos for a sample of aspect ratio Γ =61.5 over the range $15 \leq \Omega \leq 22$. Using the above four functional forms as fitting functions, we obtained results for ξ that depended only slightly on the function used, but that all had the same dependence on the distance ε from the onset of convection. In the case of the FT method, we found $\xi \sim \varepsilon^{-\nu}$ with $\nu \simeq 0.25$, consistent with previous measurements for a sample with Γ =40 but in disagreement with expectations based on the weakly nonlinear amplitude model. Fortunately the MEM was able to overcome the image-size problem of the FT method and yielded $\nu \simeq 0.46$, roughly in agreement with the theoretical models. We also determined the maximum height B of S(k) from fits of the functions to the data and found that $B \sim \varepsilon^{\beta}$ with $\beta \simeq 0.73$ for the FT method, in disagreement with the value $\beta = \frac{1}{2}$ suggested by the amplitude model. However, we note that the FT method yielded a total power proportional to $\varepsilon^{\nu+\beta}$ with $\nu+\beta \simeq 0.98$, that agrees with the theoretical expectation that $\nu + \beta = 1$. The MEM yielded β ≈ 0.63 , somewhat closer to the prediction of $\beta = \frac{1}{2}$ than the FT method.

We also showed that it is possible to present the structure factor in a scaled form that largely collapses the data onto a unique curve. This was the case for both the FT method and the MEM, even though the scaling exponents of the FT method results did not agree with the prediction from theory.

In summary, our new experimental data and analysis yielded results that differ from the earlier result that $\nu \approx 0.25$ in disagreement with theory. We have shown that this difference is due to the limitations of the FT analysis method. The MEM is capable of extracting scaling exponents from the data that are consistent with the theoretical prediction. In addition to the exponent ν , we also examined a scaling parameter β that describes the height of the structure factor, and found it to also be consistent with predictions when the MEM results were used.

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- [39] See Eq. (159) of Ch. III of Ref. [3] for the neutral curve of rotating RBC.
- [40] See EPAPS Document No. E-PLEEE8-73-105604, for an MPEG movie of a 206 \times 206 cutout (Γ^* =60) from Fig. 3 at 1500 time steps per second. This document can be reached via a direct link in the online article's HTML reference section or via the EPAPS homepage (http://www.aip.org/pubservs/epaps.html).
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